COUNTERMEASURE THREAT EMULATOR AND METHOD

TO ALL WHOM IT MAY CONCERN:

BE IT KNOWN THAT (1) C. RAY DUTTON, (2) LYNN A. POTTER, AND (3) JOSEPH B. LOPES, employees of the United States Government, citizens of the United States of America, and residents of (1) New Bedford, County of Bristol, Commonwealth of Massachusetts, (2) North Kingstown, County of Washington, State of Rhode Island, and (3) Seekonk, County of Bristol, Commonwealth of Massachusetts, have invented certain new and useful improvements entitled as set forth above of which the following is a specification.

ROBERT W. GAUTHIER, ESQ.
Reg. No. 35153
Naval Undersea Warfare Center
Division Newport
Newport, RI 02841-1708

TEL: 401-832-4736 FAX: 401-832-1231



I	Attorney Docket No. 79476
2	
3	COUNTERMEASURE THREAT EMULATOR AND METHOD
4	
5	STATEMENT OF THE GOVERNMENT INTEREST
6	The invention described herein may be manufactured and used
7	by or for the Government of the United States of America for
. 8	Governmental purposes without the payment of any royalties
_9	thereon or therefore.
10	
9 10 11 11	BACKGROUND OF THE INVENTION
1 2	(1) Field of the Invention
13 14	The present invention relates generally to torpedo
14 14	countermeasure devices and, more specifically, to programmable
1 5	apparatus and methods for emulating torpedo countermeasure
16	devices.
17	(2) Description of the Prior Art
18	Torpedo countermeasure (CM) devices are used on ships and
19	submarines to confuse incoming torpedos. Therefore, a need
20	exists for testing U.S. torpedoes with respect to foreign
21	countermeasures to determine the efficacy of U.S. torpedoes when
22	confronted by countermeasures. The current methodology of
23	testing U.S. torpedoes is to use a U.S. countermeasure device

- 1 that is thought to be representative of a possible foreign CM
- 2 device, and use this U.S. countermeasure in field tests.
- 3 However, because prior art U.S. countermeasures may not be the
- 4 same as various foreign countermeasures, are highly limited in
- 5 the type of response which may be produced especially with
- 6 respect to the requirements of emulating foreign countermeasures,
- 7° and do not have related desirable features for this purpose as
- 8 discussed below, the testing may not be as complete as may be 9 desired.

11

12

14

15

16

17

18

19

20

21

22

23

The prior art discloses various types of training required by submarines and the development of various types of acoustic devices, but does not provide a solution to the above disclosed problem and does not even appear to recognize this long felt need. Representative patents in this area include the following:

U. S. Patent No. 2,887,671, issued May 19, 1959, to Burton Frankel et al., discloses an invention pertaining to a sonar device used in the training of sonar operators to acquaint them with the characteristic sounds of a sonar ping returning from a submarine. Claim 1 states: In a sonar device, an elongated hull to be placed underwater and having a forward and an aft transducer for receiving a sonar ping, comparing means mounted in the hull for comparing the time relationship of arrival of a

given ping as received by the forward and aft transducers, means

- 1 connecting the forward and aft transducers to the comparing
- 2 means, signal generating means connected to the comparing means
- 3 for generating a signal having a characteristic which is a
- 4 function of the relationship, and transmitting transducer means
- 5 mounted on the elongated hull and connected to the signal
- 6 generating means for transmitting the generated signal.
- 7 U. S. Patent No. 5,394,376, issued Feb. 28, 1995, to
- 8 Laurence R. Riddle et al, discloses an apparatus for reducing
- $\frac{9}{2}$ acoustic radiation from an enclosure containing a fluid including
 - 10 one or more vibration sensors in communication with surfaces of
- 11 the enclosure. The vibration sensors feed signals corresponding
- $\frac{1}{2}$ to detected vibrations in the surface to a radiation filter. The
- 13 radiation filter assigns weights to the signals and generates a
- 4 summation signal which is then input to a control unit, with the
- summation signal ideally representing only those vibrations that
- 16 will actually radiate from the enclosure. The control unit uses
- 17 a reference signal and the summation signal to calculate a
- 18 cancellation waveform to offset the cause of the detected
- 19 vibrations. The cancellation signal is input to a fluid
- 20 displacement unit which applies pressure oscillations to the
- 21 fluid corresponding to the cancellation waveform.
- 22 U. S. Patent No. 4,184,209, issued Jan. 15, 1980, to Ralph
- 23 P. Crist, discloses a towed decoy system adapted to be towed from

- 1 a towing vessel, an electrically powered noisemaker, an
- 2 electrical tow cable attached to the noisemaker, a depressor
- 3 vane, a depressor cable connected to the depressor vane and to
- 4 the towing vessel, and means interconnecting the depressor cable
- 5 and the electrical tow cable at a point near the depressor vane,
- 6 the interconnecting means comprising a pair of cable grips
- 7 respectively attached at one end to adjacent sections of the
- 8 electrical tow cable and at their other ends to a snatch block
- $\frac{9}{2}$ movably mounted on the depressor cable thereby providing slack in
- =10 the electrical tow cable, whereby the noisemaker is towed at a
 - depth not less than that of the point of attachment of the snatch
- 12 block to the depressor cable.

- U. S. Patent No. 4,025,724, issued May 24, 1977, to Allen R.
- 44 Davidson, Jr. et al., discloses an array of independent sound
- 15 cancellation units arranged over a vibrating noise generating
 - 16 surface. Each unit includes an arrangement of acoustic
 - 17 transducers (sensors) positioned adjacent the surface to obtain
 - 18 an electrical average of the local acoustic noise generated by a
 - 19 predetermined zone of the surface. The summed average is changed
 - 20 in phase and gain by an active filter whose output drives an
 - 21 acoustic projector also positioned adjacent the surface and the
 - 22 acoustic output of which sums with the original noise signal in
 - 23 the acoustic far field, thus tending to cancel the noise. In

- 1 essence, each vibrating surface zone and its associated sound
- 2 cancellation unit tends to form an acoustic doublet. A signal
- 3 indicative of the projector output is used as a feedback signal,
- 4 with appropriate time delays, to cancel the effect of the
- 5 projected output signal being picked up by the unit's
- 6 transducers, and to cancel the effect of the output of other
- 7 projectors of the array.
- 8 U. S. Patent No. 5,033,028, issued July 16, 1991, to Douglas
- 9 R. Browning, discloses and describes an apparatus and method for
- ~ 10 overcoming stroke limitations of moving coil reaction-mass
- vibration dampers, by recovering armature stroke displacement.
- The coil housing is selectively coupled or de-coupled to the
- 13 vibrating structure. If, when the armature reaches its travel
- 14 limit, sufficient damping energy has not been applied to the
- [15] structure, the coil-housing assembly is decoupled from the
 - 16 structure while the armature is pulsed back to its zero
 - 17 displacement position. The housing then is re-coupled to the
 - 18 surface, having displaced some determinable distance from its
 - 19 previous location relative to the surface. Additional armature
 - 20 movement in the same direction as the previous armature stroke is
 - 21 applied, thereby generating the needed additional damping force.
 - 22 The resetting of the housing to its normal position vis-a-vis the
 - 23 vibrating structure can occur at a selected time in the damping

- 1 force-generating cycle when reset does not impart an undesired
- 2 reaction to the vibrating structure. In one implementation, a
- 3 pair of moving-coil actuators counter-drive the vibrating
- 4 structure; in another, a multiplicity of additional reaction-mass
- 5 actuators are used.
- 6 U. S. Patent No. 5,341,343, issued Aug. 23, 1994, to Robert
- 7 L. Aske, discloses an explosive actuated acoustic device which
- 8 emits sound to be used in torpedo countermeasures. Numbered
- 9 devices are delivered over an extended area and sink through the
- 410 water. The devices are actuated at different times as they sink,
- 11 to provide sound masking over an extended period of time. The
- 12 devices also include safety devices which prevent premature
- actuation from jarring or jolting and from impact with the water.
- 14 U. S. Patent No. 5,117,401, issued May 26, 1992, to Paul L.
- Feintuch, discloses an active adaptive noise canceller that
 - 16 inserts delays in the weight update logic of an adaptive filter
 - 17 employed by the canceller to make the filter stable. It has been
 - 18 found that there is a great deal of flexibility regarding the
 - 19 selection of the delay values. This insensitivity permits
 - 20 designing the delays in advance and not having to adjust them to
 - 21 different situations as they change, thus no longer requiring a
 - 22 training mode. The canceller dramatically reduces the amount of
 - 23 hardware needed to perform active adaptive noise cancelling, and

l eliminates the need for the training mode, which in some

2 applications, including automobiles, for example, can be

3 objectionable as the noise sources that are to be suppressed.

4 The above patents do not address or provide solutions to the

problem of testing torpedoes with respect to various types of

6 countermeasures. Consequently, it would be desirable to provide

7 an in-water device that can emulate known characteristics of CM

8 devices, both U.S. and foreign. It would be desirable for such a

9 device to be reusable, either stationary or mobile, and suitable

for both in-laboratory and in-water use. Moreover, it would be

desirable to provide a system that is totally programmable and

can be programmed to intercept and identify a threat waveform,

and then respond in a totally programmable manner, including pre-

programmed structured signals, broad band noise, narrow band

noise, echo repeater mode, swept LFM mode, or any one of several

16 possible randomly generated false alarm modes where the

17 transmission is a modified replica of the intercepted threat

waveform. Those skilled in the art will appreciate the present

19 invention that addresses the above and other needs and problems.

20

21

18

5

- 10

11

13

-14

15

SUMMARY OF THE INVENTION

Accordingly, it is an object of the present invention to

23 provide a countermeasure threat emulator.

- 1 It is yet another object of the present invention to provide
- 2 a means for testing domestic torpedoes against foreign
- 3 countermeasures.

[2]

- 4 These and other objects, features, and advantages of the
- 5 present invention will become apparent from the drawings, the
- 6 descriptions given herein, and the appended claims.
- 7 In accordance with the present invention, a method is
- 8 provided for testing a torpedo utilizing a countermeasure threat
- 9 emulation system which comprises steps such as selectively
- 10 programming the countermeasure threat emulation system for
- producing at least one of a plurality of foreign countermeasures
- 12 chosen from a database of foreign countermeasures. The
- countermeasure threat emulation system is controlled to operate
- 14 at a selected depth or range of depths in the water. The
- or countermeasure threat emulation system may be stationary or
 - 16 mobile. A torpedo is launched for testing with the
 - 17 countermeasure threat emulation system.
 - 18 The sounds produced by the torpedo may be analyzed with a
 - 19 neural network within the countermeasure threat emulation system.
 - 20 The analysis by the neural network results in an identification
 - 21 of the torpedo. A CPU within the countermeasure threat emulation
 - 22 system may be programmed to respond to the torpedo based on the
 - 23 identification so derived.

1 The countermeasure threat emulation system may preferably

2 operate in duplex mode by simultaneously sending and receiving

3 acoustic signals. A digital signal processing unit within the

4 countermeasure threat emulation system may be used for

5 selectively producing a large number of different types of

6 signals including a wideband acoustic signal or a band limited

7 acoustic signal.

8

3 9

10

11

12

13 U 14

15

16

17

18

19

20

21

22

23

The programmable countermeasure threat emulation system comprises a tubular housing suitable for launching from a submarine and a power supply within the tubular housing. power supply includes controls for selectively operating remotely or operating connected to an external power source. A hovering system for the tubular housing is provided for controlling a water depth of the tubular housing. A transmitter which may be comprised of a transducer stack may be used for transmitting acoustic signals. A digital signal processing unit produces waveforms to be transmitted by the transmitter. A central processing unit is used for storing digital information related to one or more countermeasure threats and supplying the digital information to the digital signal processing unit. The system also comprises a database stored in a computer external to the housing which contains a plurality of foreign countermeasure A plurality of field programmable gate arrays is

preferably provided for the digital signal processing unit so as 1

to make this unit programmable. A signal conditioner is operable 2

for converting a stream of digital signals into an analog signal 3

for broadcast by the transmitter. 4

10 10

10 12 11

12

17

18

19

20

In operation, the method comprises maintaining a database 5

having a plurality of foreign countermeasure threats. Data for 6

at least one of the plurality of foreign countermeasure threats 7

is downloaded into a computer within the countermeasure threat 8

The countermeasure threat emulator is launched for emulator.

underwater operation. An emulation of the respective foreign

countermeasure threat is transmitted into water through an

acoustic transducer. A receiver hydrophone is utilized in the

countermeasure threat emulator for receiving acoustic signals □ 13 1<u>4</u>

produced by an incoming torpedo. The incoming torpedo is

15 identified from the received acoustic signals by utilizing a

neural network within the countermeasure threat emulator and 16

responding to the incoming threat based on the identification and

a preprogrammed response for the identification.

BRIEF DESCRIPTION OF THE DRAWINGS

A more complete understanding of the invention and many of 21 the attendant advantages thereto will be readily appreciated as 22 the same becomes better understood by reference to the following 23

- 1 detailed description when considered in conjunction with the
- 2 accompanying drawings wherein corresponding reference characters
- 3 indicate corresponding parts throughout the several views of the
- 4 drawings and wherein:
- 5 FIG. 1 is a schematic representation of a countermeasure
- 6 unit in accord with the present invention; and
- 7 FIG. 2 is a schematic block diagram of countermeasure
- 8 electronics for the countermeasure unit of FIG. 1.

BRIEF DESCRIPTION OF THE PREFERRED EMBODIMENTS

- Referring now to the drawings and, more particularly, to
- 12 FIG. 1 there is shown a countermeasure threat emulator 10 in
- 13 accord with the present invention. CM threat emulator 10 may be
- 14 provided within a six inch CM housing or other size housing 12 so
- 15 as to preferably be launchable/retrievable from a torpedo tube.
 - 16 CM threat emulator 10 includes countermeasure electronics unit 14
 - 17 discussed hereinafter and shown in block diagram form in FIG. 2.
 - 18 CM threat emulator 10 is provided with hovering system 16 for
 - 19 controlling water depth, which may also be used in making CM
 - 20 threat emulator 10 mobile. While CM threat emulator 10 is
 - 21 preferably reuseable, one embodiment of CM threat emulator 10 may
 - 22 be made low enough in cost so as to be expendable by using, for
 - 23 instance, mostly salvaged components of existing countermeasure

- l devices. For remote operation, power source 18 may be used
- 2 although when tethered to surface controls, CM threat emulator 10
- 3 can be operated using external power from external control 20.
- 4 Power control electronics 19 can be provided to perform such
- 5 functions as switching between power supply sources, recharging,
- 6 and the like. Power supply 18 and/or power from external control
- 7 20 may be used to provide power to DC/DC converter 21 (see FIG.
- 8 2) for powering CM electronic unit 14.

- Preferably, CM electronic unit 14 utilizes commercial off
- 10 the shelf technology wherever possible. CM emulator electronics
 - 11 14 may include up to four digital signal processors (DSP) 22,
- 12 such as the Texas Instruments TMS320C40. In a preferred
- 13 embodiment, the main software runs on four DSP processors. DSP
- 14 processing unit 22 is interconnected with transducer interface 26
- 15 by high speed bus 24. Interface 26 preferably includes at least
 - 16 four analog channels in and four analog channels out. As well,
 - 17 interface 26 preferably includes at least sixteen channels of
 - 18 high speed digital input/output (TTL) for cooperation with high
 - 19 speed bus 24 and for use by signal conditioner and power
 - 20 amplifier 27. The analog channels may also be used in
 - 21 conjunction with signal conditioner and power amplifier 27.
 - 22 Signal conditioner/power amplifier 27 may be used to convert
 - 23 digital streams of TTL signals to analog sinusoidal waves for use

1 by a transducer stack such as transducer stack 30. Signal

2 conditioner 27 therefore connects to one of several possible

3 transducer stacks, or transmitters 30, such as an ADC MK2 array,

4 an ADC MK3 array, or a BQR-7 spherical array.

5 Signal conditioner 27 also preferably connects to a receive

6 hydrophone 28. Receive hydrophone 28 will serve to collect in-

7 water data of incoming torpedo threats from the view-point of the

8 countermeasure hydrophones. The data so collected and stored by

9 CPU 34 will be used to enhance simulation and modeling efforts,

and then verify the mathematics used in development of the other

countermeasure techniques. Thus, the memory of CPU 34 may be

downloaded into computer 32 for such analysis.

Electronics unit 14 including CPU 34 are totally programmable and can be programmed by external computer 32, such as a weapons control panel or laptop computer, to intercept and

identify a threat waveform by means discussed hereinafter, and

17 then respond in a totally programmable manner, including pre-

18 programmed structured signals, broad band noise, narrow band

19 noise, echo repeater mode, swept LFM mode, or any one of several

20 possible randomly generated false alarm modes (where the

21 transmission is a modified replica of the intercepted threat

22 waveform).

10

11

12

13 1

± 14

15

In order for CM threat emulator 10 to be programmable, CM electronics unit 14 is therefore designed to be programmable. CM

3 electronics unit 14 may be programmed to respond in any arbitrary

4 fashion or with specific characteristics. CM electronics unit

5 14 can be programmed via an alterable and updateable database 35

6 to emulate a plurality of foreign CM waveforms and signal types

7 as indicated by 36, 38, and 40. CM threat emulator 10 may also

8 be used to imitate other countermeasure devices 41 such as

9 various existing domestic countermeasure devices. The device

requirements for the CM database 35 come from the MK2, MK3, and

11 MK4 system specification documents, from available foreign

documents, and from efforts to develop operating characteristics

 \bigcirc 13 of rest of the world CM devices, and the like. Thus, the

14 information for CM database 35 has been obtained, will be updated

 $\frac{1}{2}$ 15 in the future, and is preferably maintained in one form as

16 downloadable CM database 35 for use by CPU 34.

As indicated above, CM threat emulator 10 can be made to emulate mobile threat countermeasures as well as stationary ones.

19 Preferably, CM threat emulator 10 can operate in full duplex

20 mode, receiving transmissions from receive hydrophone 28 while

21 broadcasting from transmitters 30. Depending on the selection of

22 type of countermeasure to be emulated, CM threat emulator 10 can

23

₩<u>□</u>

12

13

17

18

IJ

- 1 be programmed to operate in either a wideband or band limited
- 2 manner.

- 3 The processors provided in DSP processing unit 22 are
- 4 preferably in a format that can be used to permit a wide array of
- 5 different types of signals to be processed. Preferably, neural
- 6 network 42, such as a Ni-1000 Recognition Accelerator Chip from
- 7 Nestor and Intel is provided for pattern recognition of incoming
- 8 threats so as to identify the particular threat. Neural network
- 9 based processor 42 will be used for incorporation of research
- into classification of incoming torpedoes based on pattern
- 11 recognition of acoustic signatures processed with advanced time
- frequency distribution and wavelet algorithms.
- DSP processing unit 22 preferably includes field
- ≟14 programmable gate arrays (FPGA) and flash memories for at least
- 15 two purposes. One use will be in digital "glue logic" functions
 - 16 for consolidation of space and functional enhancement. Secondly,
 - 17 the FPGA's and flash memories may be used to provide
 - 18 reconfigurable DSP logic. FPGA technology can be used for
 - 19 construction of high speed digital signal processing logic.
 - 20 Additionally, the FPGA's are dynamically programmable, so the DSP
 - 21 processing elements can be re configured based on changing
 - 22 tactical information (for example, the FPGA's could be designed
 - 23 as a tunable digital filter, or as an iterative bank of filters),

- 1 or can possibly be reprogrammed by an advanced CM shipboard
- 2 launcher designed to use such flexibility.
- The programmability of CM threat emulator 10 makes the
- 4 system virtual, giving the CM threat emulator 10 the ability to
- 5 emulate any CM device under software control. The bulk of the
- 6 processing and control software preferably running under the
- 7 Texas Instrument's TMS320C40 digital signal processing chips may
- 8 be developed using the Pegasus Parallel Processing Design
- 9 Environment developed by Jovian Systems, Inc. The parallel C40
- 10 digital signal processor software development system may be used
- 11 to auto-generate C code suitable for use on a network of multiple
- 12 interconnect C40 modules using a graphical icon based
- =13 environment. The final product is multi-threaded and multi-
- 14 tasking executable code that can be easily distributed over the
- 15 multiple modules via the C40's high speed communication ports.
 - In summary, a relatively low cost CM threat emulator 10 may
 - 17 serve as a test platform for in-water testing of new concepts and
 - 18 technology for next generation CM device development and as a low
 - 19 cost test vehicle for U.S. Torpedo Programs requiring foreign CM
 - 20 device acoustic signatures. The present invention takes
 - 21 advantage of presently available information about foreign and
 - 22 domestic torpedo countermeasure devices to provide the technology
 - 23 for providing a virtual countermeasure concept. CM threat

- 1 emulator 10 is suitable for in-water use, where it will be
- 2 designed to be deployed from both submarine and ship platforms,
- 3 serving a dual role as a developmental platform for testing new
- 4 concepts and technology. CM threat emulator 10 also acts as a
- 5 low cost test vehicle for U.S. Torpedo Programs requiring foreign
- 6 CM device acoustical signatures for high fidelity testing of U.S.
- 7 Torpedoes.
- 8 Numerous variations of the above method are possible, some
- 9 of which have already been described. Therefore, it will be
- \mathbb{R}^{10} understood that many additional changes in the details,
- materials, steps and arrangement of parts, which have been herein
- described and illustrated in order to explain the nature of the
- invention, may be made by those skilled in the art within the
- 14 principle and scope of the invention as expressed in the appended
- 15 claims.